

Advanced Algorithms (X)

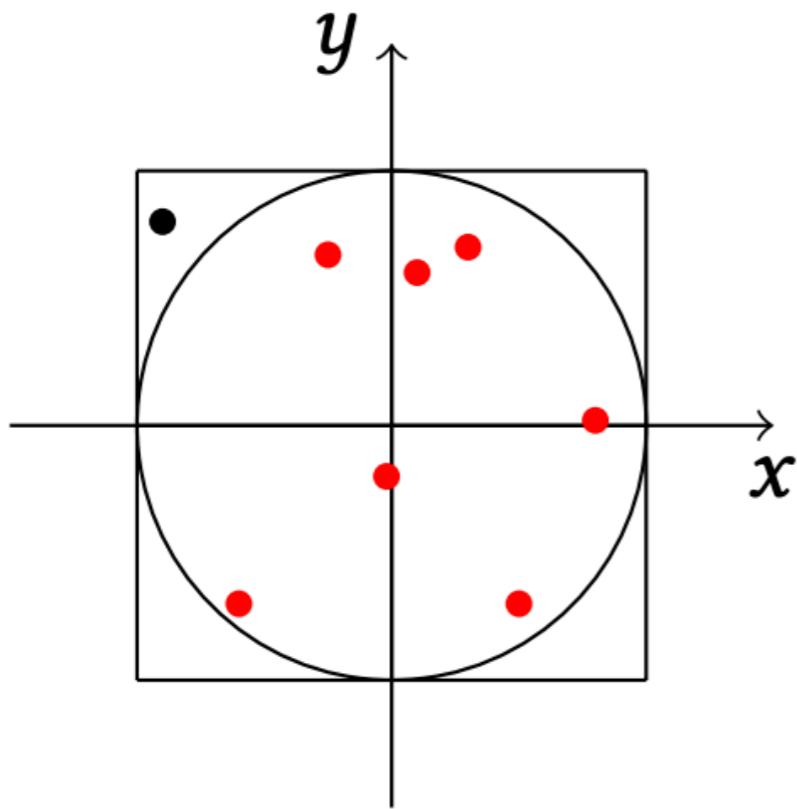
Shanghai Jiao Tong University

Chihao Zhang

May 11, 2020

Estimate π

One can design a Monte-Carlo algorithm to estimate the value of π



- $X_i \in [-1, 1] \times [-1, 1]$

- $Z_n = \sum_{i=1}^n \mathbf{1}[\|X_i\| \leq 1]$

$$X_i \sim \text{Ber} \left(\frac{\pi}{4} \right), \quad \mathbf{E}[Z_n] = \frac{\pi}{4} \cdot n$$

Therefore, by Chernoff bound

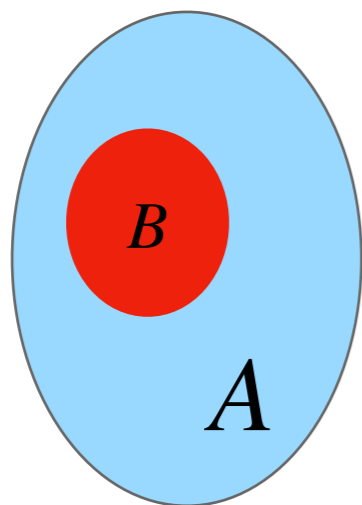
$$\Pr \left[\left| Z_n - \frac{\pi}{4} \cdot n \right| \geq \varepsilon \cdot \frac{\pi}{4} \cdot n \right] \leq 2 \exp \left(-\frac{\varepsilon^2 \pi n}{12} \right)$$

If $n \geq \frac{12}{\varepsilon^2 \pi} \log \frac{2}{\delta}$, we have an $1 \pm \varepsilon$ approximation of π with probability at least $1 - \delta$

Rejection Sampling

The method is often called **rejection sampling**

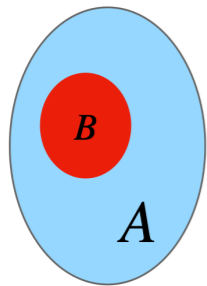
It is useful to estimate the **size** of some good sets in a large set



The number of samples is proportional to $\frac{|A|}{|B|}$

Counting DNF

A DNF formula $\varphi = C_1 \vee C_2 \vee \dots \vee C_m$, $C_i = \bigwedge_{j=1}^{\ell_i} x_{ij}$



The number of samples is
proportional to $\frac{|A|}{|B|}$

B = satisfying assignments

A = all assignments

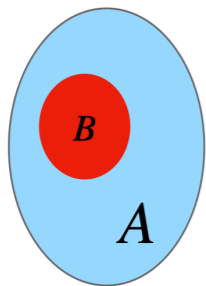
φ may contain only polynomial many solutions

The Monte Carlo method using rejection sampling
is slow!

For each clause C_i , define the set

$S_i :=$ the set of assignments satisfying C_i

We want to estimate $\left| \bigcup_{1 \leq i \leq m} S_i \right|$



The number of samples is
proportional to $\frac{|A|}{|B|}$

$$B = \bigcup_{1 \leq i \leq m} S_i$$

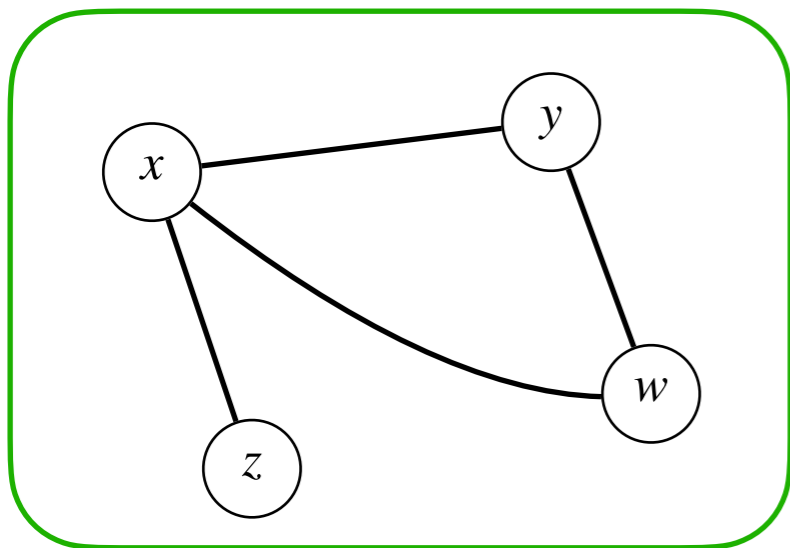
$$A = \dot{\bigcup}_{1 \leq i \leq m} S_i$$

(disjoint union)

How about CNF?

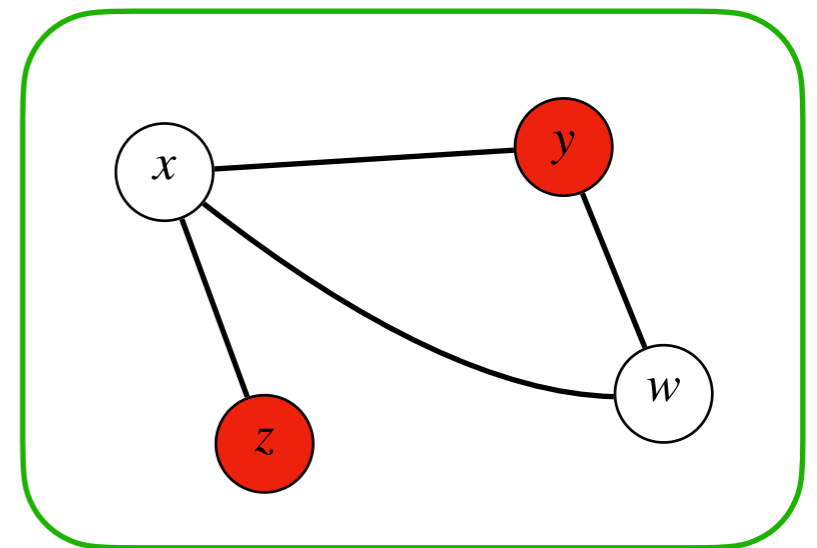
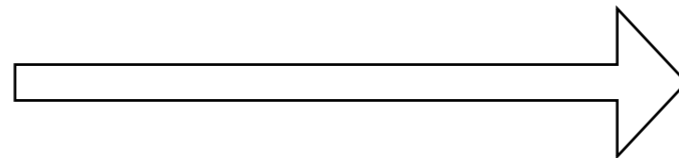
We consider a very special case: monotone 2-CNF

$$\varphi = (x \vee y) \wedge (x \vee z) \wedge (x \vee w) \wedge (y \vee w)$$



$x = \text{true}, y = \text{false}$

$z = \text{false}, w = \text{true}$



$\#\varphi = \#$ of independent sets

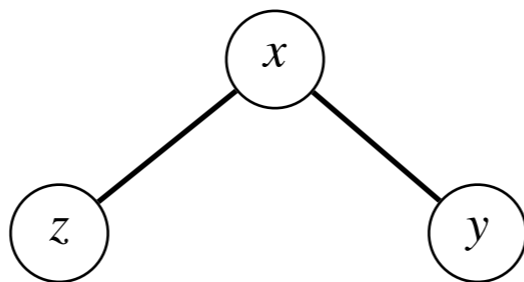
Sampling seems to be harder than DNF case...

Rejection sampling is correct but inefficient

A natural idea is to resample those violated edges...

Unfortunately, this is not correct.

Think about



Partial Rejection Sampling

Guo, Jerrum and Liu (JACM, 2019) proposed the following fix:

“Resample violated vertices and their neighbors”

We will prove the correctness and analyze its efficiency next week

From Sampling to Counting

We will show that, in many cases, if one can **sample from a space**, then he can also **estimate the size of the space**

Consider independent sets again

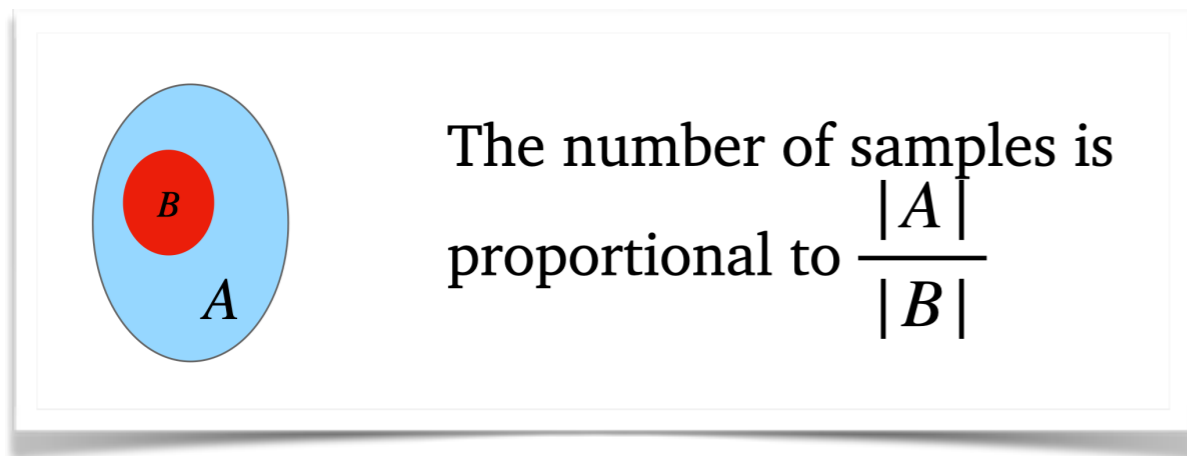
$$G = (V, E), E = \{e_1, e_2, \dots, e_m\}$$

We want to estimate $I(G)$, the number of i.s. in G

Define $G_0 = G$, $G_i = G_{i-1} - e_i$

$$|I(G)| = |I(G_0)| = \frac{|I(G_0)|}{|I(G_1)|} \cdot \frac{|I(G_1)|}{|I(G_2)|} \cdots \frac{|I(G_{m-1})|}{|I(G_m)|} \cdot |I(G_m)|$$

\parallel
 2^n



$$A = I(G_i)$$

$$B = I(G_{i+1})$$

$\frac{|A|}{|B|}$ can't be too large!

$$\frac{I(G_i)}{I(G_{i+1})} \leq 2$$

From Counting to Sampling

On the other hand, one can consecutively sample each vertex as long as $\Pr[v \in I]$ is known

The value can be obtained via a **counting oracle**

The above two reductions require the system to satisfy “**self-reducible**” property