

[AI2613 Lecture 12] Gaussian Processes, Brownian Bridge

June 9, 2023

1 Gaussian Processes and Brownian Motion

In the last lecture, we defined the standard Brownian motion:

Definition 1 (Standard Brownian Motion / Wiener Process). We say a stochastic process $\{W(t)\}_{t \geq 0}$ is a standard Brownian motion or Wiener process if it satisfies

- $W(0) = 0$;
- **Independent increments:** $\forall 0 \leq t_0 \leq t_1 \leq \dots \leq t_n, W(t_1) - W(t_0), W(t_2) - W(t_1), \dots, W(t_n) - W(t_{n-1})$ are mutually independent;
- **Stationary increments:** $\forall s, t > 0, W(s+t) - W(s) \sim \mathcal{N}(0, t)$;
- $W(t)$ is continuous almost surely.¹

Today we will give another characterization of Brownian motions in terms of the *Gaussian process*. First recall the notion of high dimensional Gaussian distribution. A vector of random variables (X_1, X_2, \dots, X_n) is said to be Gaussian iff $\forall a_1, a_2, \dots, a_n, \sum_{i=1}^n a_i X_i$ is a one-dimensional Gaussian. Let $\mu = (\mu_1, \mu_2, \dots, \mu_n)$ where $\mu_i = \mathbf{E}[X_i]$. Let $\Sigma = (\text{Cov}(X_i, X_j))_{i,j}$. Then the probability density function f of (X_1, X_2, \dots, X_n) is

$$\text{for } x = (x_1, x_2, \dots, x_n), f(x) = (2\pi)^{-\frac{n}{2}} \cdot |\det \Sigma|^{-\frac{1}{2}} \cdot e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}.$$

Definition 2 (Gaussian Process). A stochastic process $\{X(t)\}_{t \geq 0}$ is called Gaussian process if $\forall 0 \leq t_1 \leq t_2 \leq \dots \leq t_n, (X(t_1), X(t_2), \dots, X(t_n))$ is Gaussian.

Note that a Gaussian vector can be characterized by its mean vector and the covariance matrix. Standard Brownian motion is a special family of Gaussian processes where the covariance of $X(s)$ and $X(t)$ is $s \wedge t$.

Definition 3 (Standard Brownian Motion/Standard Wiener Process). We say a stochastic process $\{W(t)\}_{t \geq 0}$ is a standard Brownian motion or Wiener process if it satisfies

- $\{W(t)\}_{t \geq 0}$ is an almost surely continuous Gaussian Process;
- $\forall s \geq 0, \mathbf{E}[W(s)] = 0$;
- $\forall 0 \leq s \leq t, \text{Cov}(W(s), W(t)) = s$.

We will show that it is easier to use Definition 3 to verify that a certain stochastic process is a Brownian motion. Let us first verify that the two definitions are equivalent.

¹ Let Ω be the sample space. Then W can be viewed as a mapping from $\mathbb{R} \times \Omega$ to \mathbb{R} . The meaning of “ $W(t)$ is continuous almost surely” is: $\exists \Omega_0 \subseteq \Omega$ with $\Pr[\Omega_0] = 1$ such that $\forall \omega \in \Omega_0, W(t, \omega)$ is continuous with regard to t .

Proposition 4. *The two definitions of standard Brownian motions are equivalent.*

Proof. Given Definition 1, it is easy to know that $E[W(s)] = 0$ for all $s \geq 0$ since $W(s) \sim \mathcal{N}(0, s)$. What we need is to verify that $\{W(t)\}_{t \geq 0}$ in Definition 1 is a Gaussian process and to compute the covariance of $W(s)$ and $W(t)$ in Definition 1.

Note that $\forall 0 \leq s < t$ and $\forall a, b$, we have

$$aW(s) + bW(t) = (a + b)W(s) + b(W(t) - W(s)).$$

Since $W(s)$ and $W(t) - W(s)$ are two independent Gaussian's, $aW(s) + bW(t)$ is still a Gaussian.

By the distributive law of covariance, for any $0 \leq s \leq t$, we have

$$\begin{aligned} \text{Cov}(W(s), W(t)) &= \text{Cov}(W(s), W(t) - W(s) + W(s)) \\ &= \text{Cov}(W(s), W(t) - W(s)) + \text{Cov}(W(s), W(s)) \\ &= \text{Var}[W(s)] = s. \end{aligned}$$

Then we consider the counterpart. Given Definition 3, we can deduce the first and fourth property in Definition 1 directly. For any $0 \leq t_{i-1} \leq t_i \leq t_{j-1} \leq t_j$, we have

$$\begin{aligned} &\text{Cov}(W(t_i) - W(t_{i-1}), W(t_j) - W(t_{j-1})) \\ &= \text{Cov}(W(t_i), W(t_j)) + \text{Cov}(W(t_{i-1}), W(t_{j-1})) \\ &\quad - \text{Cov}(W(t_i), W(t_{j-1})) - \text{Cov}(W(t_{i-1}), W(t_j)) \\ &= t_i + t_{i-1} - t_i - t_{i-1} = 0, \end{aligned}$$

which yields the independence of $W(t_i) - W(t_{i-1})$ and $W(t_j) - W(t_{j-1})$. Thus, the $\{W(t)\}_{t \geq 0}$ in Definition 3 satisfies independent increments.

It is easy to verify that $\forall s, t > 0$, $W(s + t) - W(s)$ is a Gaussian with mean 0. Note that

$$\begin{aligned} \text{Var}[W(t + s) - W(s)] &= E[(W(t + s) - W(s))^2] \\ &= E[W(t + s)^2] + E[W(s)^2] - 2E[W(t + s)W(s)] \\ &= \text{Var}[W(t + s)^2] + \text{Var}[W(s)^2] - 2\text{Cov}(W(t + s), W(s)) \\ &= t + s + s - 2s = t. \end{aligned}$$

Thus, the $\{W(t)\}_{t \geq 0}$ in Definition 3 satisfies stationary increments. □

Example 1. *Suppose $\{W(t)\}_{t \geq 0}$ is a standard Brownian motion. We claim that $\{X(t)\}_{t \geq 0}$ is also a standard Brownian motion where $X(0) = 0$ and $X(t) = t \cdot W(\frac{1}{t})$ for $t > 0$.*

We verify the three requirements in Definition 3.

Since $X(t) = t \cdot W(\frac{1}{t})$ which is the composition of two (almost surely) continuous function, $\{X(t)\}_{t \geq 0}$ is continuous almost surely as well. For any

It is worth noting that the sum of two Gaussians is not necessarily a Gaussian, unless they are joint Gaussian. Independence is just a special case of joint Gaussian (the covariance is zero).

a_1, a_2, \dots, a_n and $t_1, t_2, \dots, t_n \geq 0$, $\sum_{i=1}^n a_i X(t_i) = \sum_{i=1}^n a_i t_i \cdot W(\frac{1}{t_i})$. Since $\{W(t)\}$ is standard Brownian motion, $\sum_{i=1}^n a_i t_i \cdot W(\frac{1}{t_i})$ is Gaussian. Thus, $\{X(t)\}_{t \geq 0}$ is a Gaussian process. For $0 \leq s < t$,

$$\begin{aligned} \text{Cov}(X(s), X(t)) &= \text{Cov}(sW(\frac{1}{s}), tW(\frac{1}{t})) \\ &= st \cdot \text{Cov}(W(\frac{1}{s}), W(\frac{1}{t})) \\ &= st \cdot \frac{1}{t} = s. \end{aligned}$$

Thus, $\{X(t)\}_{t \geq 0}$ is a standard Brownian motion.

2 Brownian Bridge

In the last lecture, we already calculated the distribution of $W(t)$ conditioned on $W(u) = x$ for some $u \geq t$. We use $X(t)$ to denote this process, and $X(t)$ is usually called a *Brownian bridge*.

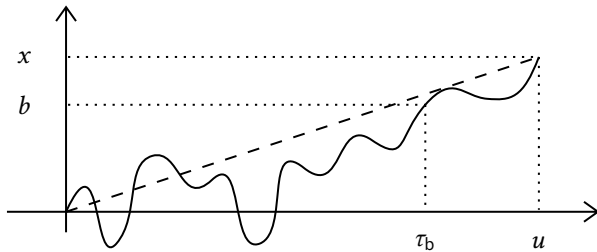


Figure 1: A Brownian bridge

We know from previous calculations that $X(t) \sim N(\frac{t}{u}x, \frac{t(u-t)}{u})$ is a Gaussian. Since the *conditional distribution of a multidimensional Gaussian distribution is Gaussian as well*, $X(t)$ is a Gaussian process. As a result, it is useful to compute the covariance of this process.

Recall $W(t)$ is a standard Brownian motion. For any $s \leq t$, we have

$$\begin{aligned} &\text{Cov}(X(s), X(t)) \\ &= \text{Cov}(W(s), W(t) \mid W(u) = x) \\ &= \mathbf{E}[W(s) \cdot W(t) \mid W(u) = x] - \mathbf{E}[W(s) \mid W(u) = x] \cdot \mathbf{E}[W(t) \mid W(u) = x] \\ &= \int_{-\infty}^{\infty} y \mathbf{E}[W(s) \mid W(t) = y, W(u) = x] \cdot f_{W(t) \mid W(u)}(y \mid x) dy - \frac{st}{u^2} x^2. \\ &= \frac{s}{t} \mathbf{E}[W(t)^2 \mid W(u) = x] - \frac{st}{u^2} x^2 \\ &= \frac{s(u-t)}{u}. \end{aligned}$$

$$\mathbf{E}[W(t)^2 \mid W(u) = x] = \text{Var}[X(t)] + \mathbf{E}[X(t)]^2$$

Definition 5 (Standard Brownian Bridge). *A standard Brownian motion ending at $W(1) = 0$ is called a standard Brownian bridge.*

We can verify that $X(t) = W(t) - tW(1)$ is a standard Brownian bridge by calculating its mean and covariances.

Again like we did in the last lecture, we can compute the hitting time of a standard Brownian bridge using the principle of reflection.

Example 2 (Hitting Time in a Brownian Bridge). *Let $\{W(t)\}_{t \geq 0}$ be a standard Brownian motion. Let $\tau_b \triangleq \inf \{t \geq 0 \mid W(t) > b\}$. Then we compute $\Pr [\tau_b < u \mid W(u) = x]$. Note that if $b < x$, $\Pr [\tau_b < u \mid W(u) = x] = 1$. Let ψ be the probability density function of standard Gaussian distribution, that is, $\psi(x) = \frac{1}{\sqrt{2\pi}} \cdot e^{-\frac{x^2}{2}}$. If $b > x$, letting dx be an infinitesimal change, we have*

$$\begin{aligned} \Pr [\tau_b < u \mid W(u) = x] &= \frac{\Pr [\tau_b < u \wedge W(u) \in [x, x + dx]]}{\Pr [W(u) \in [x, x + dx]]} \\ &= \frac{\Pr [\tau_b < u] \cdot \Pr [W(u) \in [x, x + dx] \mid \tau_b < u]}{f_u(x) dx}. \end{aligned}$$

If we have known the value of τ_b and $\tau_b < u$, we can regard $\{W(u)\}_{t \geq \tau_b}$ as a Brownian motion starting from b . Then we have

$$\begin{aligned} \Pr [\tau_b < u] \cdot \Pr [W(u) \in [x, x + dx] \mid \tau_b < u] &= \Pr [\tau_b < u] \cdot \Pr [W(u) \in [2b - x - dx, 2b - x] \mid \tau_b < u] \\ &= \Pr [\tau_b < u \wedge W(u) \in [2b - x - dx, 2b - x]] \\ &= \Pr [W(u) \in [2b - x - dx, 2b - x]] \\ &= f_u(2b - x) dx \end{aligned}$$

Thus, when $b > x$, $\Pr [\tau_b < u \mid W(u) = x] = \frac{f_u(2b-x)}{f_u(x)} = e^{-\frac{2b(b-x)}{u}}$.

When $b = x$, we have

$$\Pr [\tau_b < u \mid W(u) = b] = \frac{\Pr [\tau_b < u \wedge W(u) \in [b, b + db]]}{\Pr [W(u) \in [b, b + db]]}.$$

Note that

$$\Pr [\tau_b < u \wedge W(u) \in [b, b + db]] = \Pr [\tau_b < u] - \Pr [\tau_b < u \wedge W(u) > b + db] - \Pr [\tau_b < u \wedge W(u) < b]. \quad (1)$$

We know that $\Pr [\tau_b < u] = 2 \left(1 - \Phi \left(\frac{b}{\sqrt{u}}\right)\right)$. Note that

$$\begin{aligned} \Pr [\tau_b < u \wedge W(u) > b + db] &= \Pr [W(u) > b + db] \\ &= 1 - \Phi \left(\frac{b}{\sqrt{u}}\right) - \Pr [W(u) \in [b, b + db]]. \end{aligned}$$

And

$$\begin{aligned} \Pr [\tau_b < u \wedge W(u) < b] &= \Pr [\tau_b < u] \cdot \Pr [W(u) < b \mid \tau_b < u] \\ &= \frac{1}{2} \cdot \Pr [\tau_b < u] = 1 - \Phi \left(\frac{b}{\sqrt{u}}\right). \end{aligned}$$

Thus, Equation (1) equals to $\Pr [W(u) \in [b, b + db]]$ and

$$\Pr [\tau_b < u \mid W(u) = b] = 1.$$

3 Kolmogorov-Smirnov Test

In this section, we introduce an application of Brownian Bridge, the Kolmogorov-Smirnov test.

Suppose that U_1, U_2, \dots, U_n are independently sampled from some distribution $[0, 1]$ with CDF F . We would like to check if it is a uniform distribution, i.e., if the F satisfies $F(t) = t$ for every $t \in [0, 1]$.

Let \widehat{F}_n be the empirical cumulative distribution function, that is, for $t \in [0, 1]$, $\widehat{F}_n(t) = \frac{1}{n} \sum_{i=1}^n \mathbf{1}[U_i \leq t]$. It then follows from the law of large numbers that

$$\widehat{F}_n(t) \xrightarrow{n \rightarrow \infty} \mathbf{E} \left[\widehat{F}_n(t) \right] = \frac{1}{n} \sum_{i=1}^n \Pr [U_i \leq t] = F(t).$$

The idea of Kolmogorov-Smirnov test is to monitor the variable $\widehat{F}_n(t) - t$ for every $t \in [0, 1]$ and reject the uniformity hypothesis if there exists some t that $|\widehat{F}_n(t) - t|$ is large. Then our goal is to find a suitable rejection threshold b such that if F is indeed a uniform distribution, the failure probability $\lim_{n \rightarrow \infty} \Pr \left[\max_{t \in [0, 1]} |\widehat{F}_n(t) - t| \geq b \right]$ is sufficiently small (i.e., $\leq \frac{1}{100}$). If F is a uniform distribution, for a fixed t , we have

$$\begin{aligned} \mathbf{E} \left[\widehat{F}_n(t) \right] &= F(t) = t; \\ \mathbf{Var} \left[\widehat{F}_n(t) \right] &= \frac{1}{n^2} \sum_{i=1}^n \mathbf{Var} [\mathbf{1}[U_i \leq t]] = \frac{1}{n} \cdot t(1-t). \end{aligned}$$

Let $X_n(t) \triangleq \sqrt{n} \cdot (\widehat{F}_n(t) - t)$ for $t \in [0, 1]$. By the Central Limit Theorem, we have $X_n(t) \sim \mathcal{N}(0, t(1-t))$ when $n \rightarrow \infty$. For any $0 \leq s \leq t \leq 1$,

$$\begin{aligned} \text{Cov}(X_n(s), X_n(t)) &= n \cdot \text{Cov} \left(\widehat{F}_n(s) - s, \widehat{F}_n(t) - t \right) \\ &= \frac{1}{n} \text{Cov} \left(\sum_{i=1}^n \mathbf{1}[U_i \leq s], \sum_{i=1}^n \mathbf{1}[U_i \leq t] \right) \\ &= \text{Cov} (\mathbf{1}[U_1 \leq s], \mathbf{1}[U_1 \leq t]) \\ &= \Pr [U_1 \leq s, U_1 \leq t] - \Pr [U_1 \leq s] \Pr [U_1 \leq t] \\ &= s(1-t). \end{aligned}$$

For any $0 \leq t_1 \leq t_2 \leq \dots \leq t_k \leq 1$, let $\Sigma = (\text{Cov}(X_n(t_i), X_n(t_j)))_{i,j}$. It follows from the high-dimensional Central Limit Theorem that

$$(X_n(t_1), X_n(t_2), \dots, X_n(t_k))^T \xrightarrow{D} \mathcal{N}(\mathbf{0}, \Sigma) \sim (X(t_1), X(t_2), \dots, X(t_k))^T,$$

where $\{X(t)\}$ is a standard Brownian Bridge. Then using the result in Example 2, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} \Pr \left[\max_{t \in [0, 1]} \widehat{F}_n(t) - t \geq b \right] &= \Pr \left[\max_{t \in [0, 1]} X(t) \geq \sqrt{nb} \right] \\ &= \Pr \left[\tau_{\sqrt{nb}} < 1 \mid W(1) = 0 \right] = \exp\{-2nb^2\}. \end{aligned}$$